

①

STIFFNESS BY DEFINITION

CES 4141

GOAL: IDENTIFY (DERIVE) STIFFNESS MATRIX K
OF FRAMES & TRUSS SYSTEMS

PROPERTIES OF K

1. FUNCTION OF SYSTEM GEOMETRY, MATERIAL PROPERTIES, AND BOUNDARY CONDITIONS
2. NOT A FUNCTION OF EXTERNAL LOADS
3. K ALWAYS SQUARE, SYMMETRIC MATRIX ($K_{ij} = K_{ji}$)
4. DIAGONAL TERMS ALWAYS POSITIVE $K_{ij} = +$
FOR $i = j$

DEFINITION

K_{ij} = FORCE (MOMENT) REQUIRED AT D.O.F. i TO HOLD A UNIT DEFLECTION AT D.O.F. j , WHILE HOLDING ALL OTHER D.O.F. = 0

ANALYSIS USING STIFFNESS MATRIX APPROACH

EQ. 1

$$K \cdot \mathbf{f} = \mathbf{R}$$

K - STIFFNESS

\mathbf{f} - UNKNOWN DISPLACEMENTS

\mathbf{R} - KNOWN EXTERNAL FORCES

- I. DERIVE K FOR STRUCTURE
- II. EXPRESS EXTERNAL LOADS IN \mathbf{R}
- III. SOLVE EQ. 1 FOR DISPLACEMENTS \mathbf{f}
- IV. FIND INTERNAL MOMENTS USING SLOPE DEFLECTION

STIFFNESS BY DEFINITION

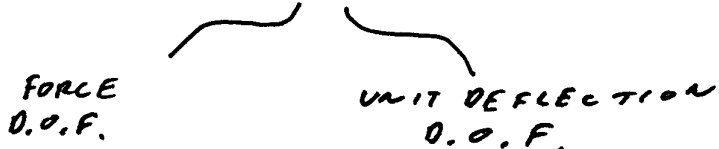
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PROCEDURE

1. DRAW STRUCTURE WITH NO EXTERNAL LOADS
2. IDENTIFY D.O.F. AND LABEL V_1, V_2, \dots ETC.
3. STARTING WITH FIRST COLUMN IN K , DRAW DEFLECTED SHAPE ACCORDING TO DEFINITION OF K_{ij}

FOR COLUMN 1, DRAW $V_1=1, V_2=0, V_3=0, \dots$

FOR COLUMN 2, $V_1=0, V_2=1, V_3=0, \dots$
4. ON DEFLECTED SHAPE FIGURES, ADD A MOMENT OR FORCE AT EVERY D.O.F., ASSUMING POSITIVE DIRECTION.
5. LABEL THESE FORCES/MOMENTS ACCORDING TO DEFINITION OF K_{ij}



FORCE
D.O.F.

UNIT DEFLECTION
D.O.F.
6. BREAK STRUCTURE UP INTO THE F.B.D.'S NEEDED TO EXPRESS K_{ij} 'S IN TERMS OF INTERNAL UNKNOWN MOMENTS M_{ij}

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STIFFNESS BY DEFINITION
PROCEDURE CONT.

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7. USE SLOPE DEFLECTION EQUATION

$$M_{ij} = \frac{2EI}{L_{ij}} \left(2\theta_i + \theta_j + \frac{3D}{L_{ij}} \right)$$

AND DEFINITION OF COLUMN DISPLACEMENTS
TO SOLVE FOR M_{ij} IN F.B.D.S IN
STEP 6

8. SOLVE FOR K_{ij} TERMS USING EQUILIBRIUM
EQS. FROM 6. , \rightarrow M_{ij} FROM 7.

9. MOVE TO COLUMN 2 AND REPEAT FROM
STEP 3. , THEN COLUMN 3, ETC.
UNTIL ALL K_{ij} ARE DEFINED

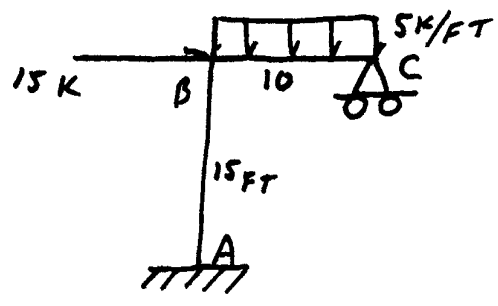
MAX $i = j = \#$ OF D.O.F.

* SAME PROCEDURE FOR BOTH DET. \rightarrow INDET. SYSTEMS!

EXAMPLES FOLLOW

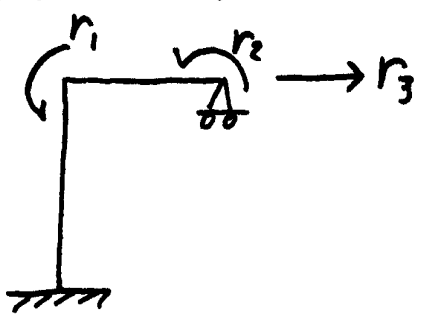
STIFFNESS BY DEFINITION

EXAMPLE 1



FIND DEFLECTIONS, ROTATIONS, REACTIONS, V/M DIAGRAM

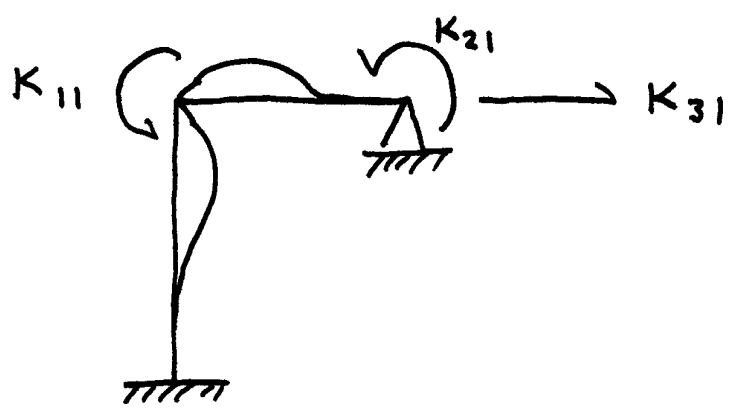
- 1. REDRAW W/OUT LOADS
- 2. ID + LABEL D.O.F.



$\curvearrowright \rightarrow +$

$$K = \begin{bmatrix} ? \\ ? \\ ? \end{bmatrix}_{3 \times 3}$$

- 3. COLUMN #1, $r_1=1$ $r_2=0$ $r_3=0$
DRAW SHAPE
- 4. ADD MOMENT OR FORCE AT EACH D.O.F. IN + DIRECTION
- 5. LABEL FORCES ACCORDING TO K_{ij} DEFINITION

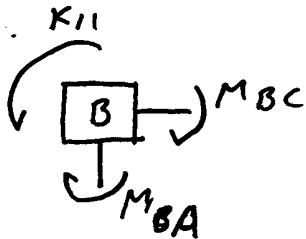
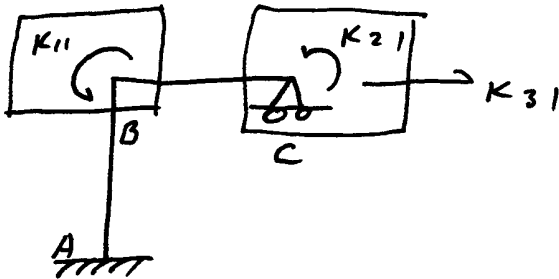


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EXAMPLE 1 CONT.

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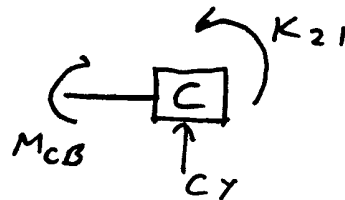
6. BREAK INTO F.B.D.S TO EXPRESS K_{11}, K_{21}, K_{31} IN TERMS OF INTERNAL MOMENTS



ΣM

$K_{11} = M_{BA} + M_{BC}$

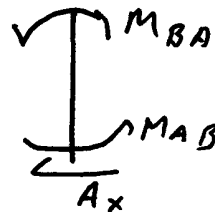
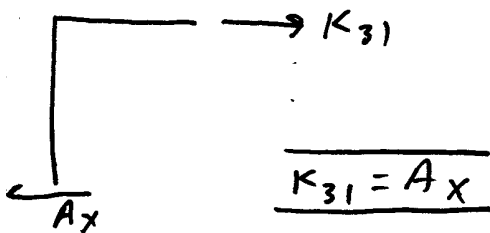
①



ΣM

$K_{21} = M_{CB}$

②



$\Sigma M_B = 0 = M_{BA} + M_{AB} = A_x \cdot L_{AB}$

ΣM

$K_{31} = \frac{M_{BA} + M_{AB}}{L_{AB}}$

③

NOW FIND
 $M_{BA}, M_{BC}, M_{CB}, M_{AB}$
 AND PLUG IN TO ①, ②, ③

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EXAMPLE 1 CONT.

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7. SOLVE FOR M_{ij} IN 3 EQUILIBRIUM EQS. FROM 6. USING

$$M_{ij} = \frac{2EI}{L} \left(2\theta_i + \theta_j + \frac{3\Delta}{L} \right)$$

→

$$r_1 = 1 \quad r_2 = 0 \quad r_3 = 0$$

FOR K_{11}

$$M_{BA} = \frac{2EI}{L_{AB}} \left(2\theta_B + \theta_A + \frac{3\Delta}{L} \right)$$

$$\theta_B = r_1 = 1$$

$$\theta_A = 0 \quad \text{NOT A D.O.F.}$$

$$\Delta = r_3 = 0$$

$$M_{BA} = \frac{2EI}{L_{AB}} \cdot 2r_1 = \frac{4EI}{L_{AB}} = M_{BA}$$

$$M_{BC} = \frac{2EI}{L_{BC}} \left(2\theta_B + \theta_C + \frac{3\Delta}{L} \right) = \frac{2EI}{L_{BC}} \left(2r_1 + r_2 + 0 \right)$$

$$M_{BC} = \frac{4EI}{L_{BC}}$$

$$K_{11} = \frac{4EI}{L_{AB}} + \frac{4EI}{L_{BC}}$$

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EXAMPLE 1 CONT.

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FOR K_{21}

$$M_{CB} = \frac{2EI}{L_{CB}} \left(2\theta_C + \theta_B + \frac{3D}{L_{CB}} \right) = \frac{2EI}{L_{CB}} \left(2\cancel{\theta_2} + \cancel{\theta_1} + 0 \right)$$

$$M_{CB} = \boxed{K_{21} = \frac{2EI}{L_{CB}}}$$

FOR K_{31}

$$M_{AB} = \frac{2EI}{L_{AB}} \left(2\theta_A + \theta_B + \frac{3D}{L} \right) = \frac{2EI}{L_{AB}} \left(0 + \cancel{\theta_1} + \frac{3\cancel{\theta_2}}{L_{AB}} \right)$$

$$\boxed{\begin{array}{l} M_{AB} = \frac{2EI}{L_{AB}} \\ \hline M_{BA} = \frac{4EI}{L_{AB}} \end{array}}$$

FROM BEFORE

$$K_{31} = \frac{M_{BA} + M_{AB}}{L_{AB}} = \boxed{\frac{6EI}{L_{AB}^2} = K_{31}}$$

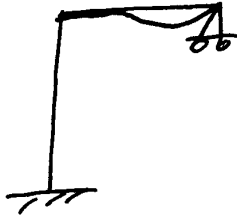
DONE WITH COLUMN 1
SO FAR WE HAVE

$$K = \left[\begin{array}{ccc} \frac{4EI}{L_{AB}} + \frac{4EI}{L_{BC}} & ? K_{12} & ? K_{13} \\ \frac{2EI}{L_{CB}} & ? K_{22} & ? K_{23} \\ \frac{6EI}{L_{AB}^2} & ? K_{32} & ? K_{33} \end{array} \right]$$

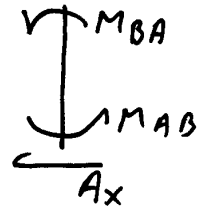
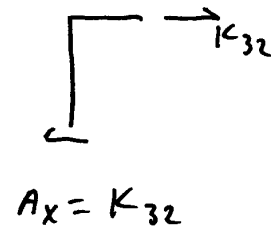
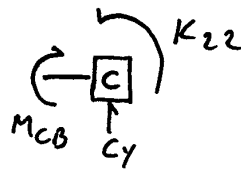
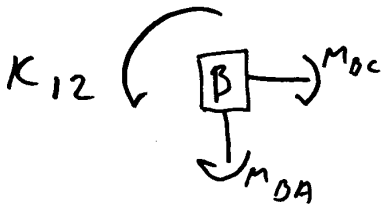
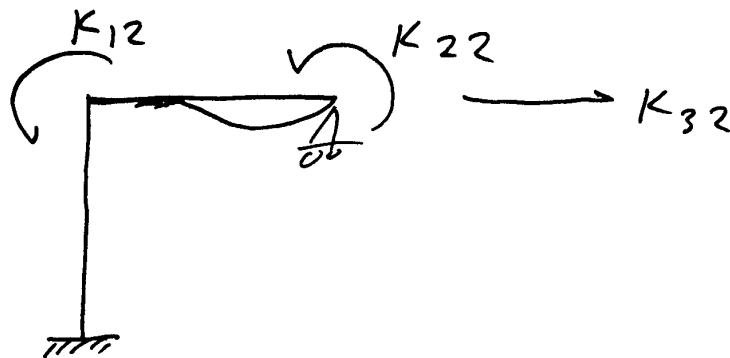
EXAMPLE 1 CONTINUED

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CONTINUE PROCESS FOR COLUMN 2



$$\begin{aligned} r_1 &= 0 & = \theta_B \\ r_2 &= 1 & = \theta_C \\ r_3 &= 0 & = \Delta \end{aligned}$$



$K_{12} = M_{BA} + M_{BC}$ ①	$K_{22} = M_{CB}$ ②	$K_{32} = \frac{M_{AB} + M_{BA}}{L_{AB}}$ ③
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* NOTE: FROM ONE COLUMN IN K TO NEXT, SAME 3 F.B.D.'S ARE USED, AND SAME 3 EQUIL. EQS. RESULT EXCEPT K_{11} BECOMES K_{22} , K_{21} BECOMES K_{22} , $K_{31} \Rightarrow K_{32}$

EXAMPLE 1 CONT.

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ALTHOUGH F.P.O.'S & EQUILIBRIUM EQS. ARE SAME AS FIRST COLUMN, WE MUST REDEFINE M_{AB} , M_{BA} , M_{BC} , M_{CB}

C1 $v_1 = 1$ $v_2 = v_3 = 0$

C2 $v_1 = 0$ $v_2 = 1$ $v_3 = 0$

$$M_{AB} = \frac{2EI}{L_{AB}} \left(0 + \cancel{v_1}^0 + \frac{3\cancel{v_3}^0}{L_{AB}} \right) = 0$$

$$M_{BA} = \frac{2EI}{L_{AB}} \left(2\cancel{v_1}^0 + 0 + \frac{3\cancel{v_3}^0}{L_{AB}} \right) = 0$$

$$M_{BC} = \frac{2EI}{L_{BC}} \left(2\cancel{v_1}^0 + \cancel{v_2}^1 + 0 \right) = \frac{2EI}{L_{BC}}$$

$$M_{CB} = \frac{2EI}{L_{BC}} \left(2\cancel{v_2}^1 + \cancel{v_1}^0 + 0 \right) = \frac{4EI}{L_{BC}}$$

$$K_{12} = 0 + \frac{2EI}{L_{BC}}$$

$$K_{22} = \frac{4EI}{L_{BC}}$$

$$K_{32} = \frac{0+0}{L_{AB}} = 0$$

EXAMPLE 1 CONT.

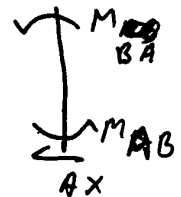
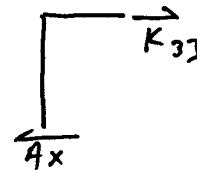
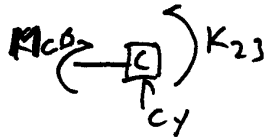
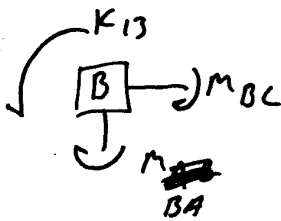
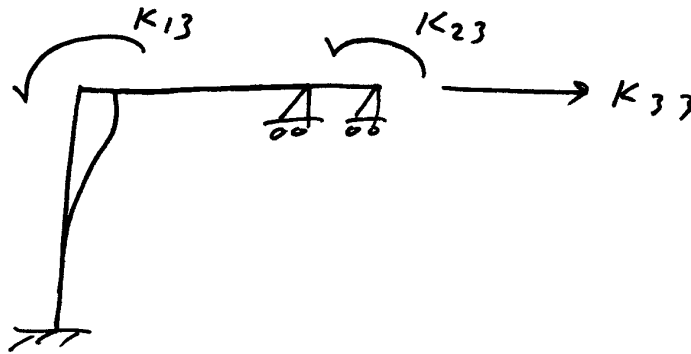
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SO FAR ...

$$K = \begin{bmatrix} \frac{4EI}{L_{AB}} + \frac{4EI}{L_{BC}} & \frac{2EI}{L_{CB}} & ? K_{13} \\ \frac{2EI}{L_{CB}} & \frac{4EI}{L_{BC}} & ? K_{23} \\ \frac{6EI}{L^2_{AB}} & 0 & ? K_{33} \end{bmatrix}$$

FINALLY, COLUMN 3

$$r_1 = 0 \quad r_2 = 0 \quad r_3 = 1$$



$$K_{13} = M_{BC} + M_{BA} \quad K_{23} = M_{CB} \quad K_{33} = \frac{M_{AB} + M_{BA}}{L_{AB}}$$

AGAIN, SAME 3 F.B.D.'S → SAME 3

EQUIL. EQS., JUST K'S CHANGE

$$K_{11} = K_{12} = K_{13} = M_{BC} + M_{CB}$$

$$K_{21} = K_{22} = K_{23} = M_{CB}$$

$$K_{31} = K_{32} = K_{33} = (M_{AB} + M_{BA})/L_{AB}$$

EXAMPLE 1 CONT.

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(11)

REDEFINE M_{ij} 's

$$M_{AB} = \frac{2EI}{L_{AB}} \left(0 + \cancel{X_1^0} + \frac{3\cancel{X_3^1}}{L_{AB}} \right) = \frac{6EI}{L_{AB}^2}$$

$$M_{BA} = \frac{2EI}{L_{AB}} \left(2\cancel{X_1^0} + 0 + \frac{3\cancel{X_3^1}}{L_{AB}} \right) = \frac{6EI}{L_{AB}^2}$$

$$M_{BC} = \frac{2EI}{L_{BC}} \left(2\cancel{X_1^0} + \cancel{X_2^0} + 0 \right) = 0$$

$$M_{CB} = \frac{2EI}{L_{BC}} \left(2\cancel{X_2^0} + \cancel{X_1^0} + 0 \right) = 0$$

$$K_{13} = \frac{6EI}{L_{AB}^2}$$

$$K_{23} = 0$$

$$K_{33} = \frac{12EI}{L_{AB}^3}$$

PUT IT ALL TOGETHER ...

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$$K = \begin{bmatrix} \frac{4EI}{L_{AB}} + \frac{4EI}{L_{BC}} & \frac{2EI}{L_{CB}} & \frac{6EI}{L_{AB}^2} \\ \frac{2EI}{L_{CB}} & \frac{4EI}{L_{BC}} & 0 \\ \frac{6EI}{L_{AB}^2} & 0 & \frac{12EI}{L_{AB}^3} \end{bmatrix}$$

* A QUICK CHECK ... IS K SYMMETRIC?

$$K_{ij} = K_{ji} \quad \text{FOR } i \neq j \quad ?$$

$$K_{12} = K_{21} \quad \checkmark$$

$$K_{13} = K_{31} \quad \checkmark$$

$$K_{32} = K_{23} \quad \checkmark$$

* A QUICK CHECK ... ARE DIAGONAL TERMS \oplus ?

$$K_{11} = + \quad \checkmark$$

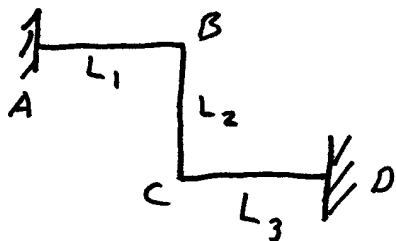
$$K_{22} = + \quad \checkmark$$

$$K_{33} = + \quad \checkmark$$

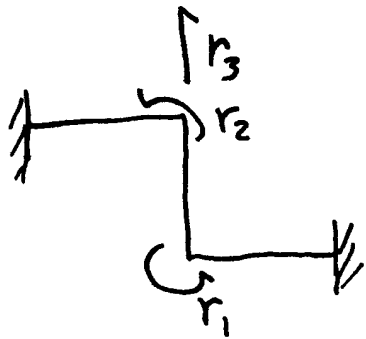
EXAMPLE 2

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BEFORE WE GET TO LOADS AND SOLVING FOR DISPLACEMENTS, WE'LL DO ANOTHER EXAMPLE IN A MORE ORGANIZED WAY.



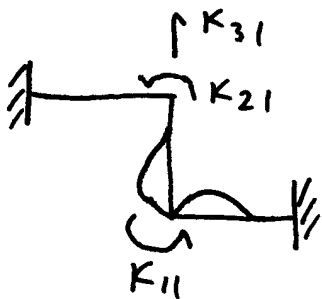
FIND STIFFNESS MATRIX K



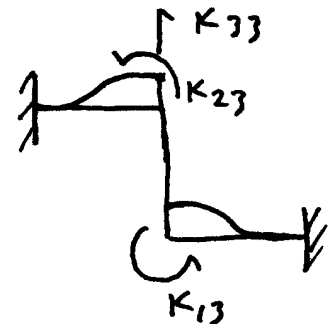
3 D.O.F.

3 DEFLECTED SHAPES

C1 $r_1 = 1$ $r_2 = r_3 = 0$



C3 $r_1 = r_2 = 0$ $r_3 = 1$



C2
 $r_1 = r_3 = 0$ $r_2 = 1$

EXAMPLE 2 CONT.

EXPAND ALL M_{ij} NEEDED

$$M_{AB} = \frac{2EI}{L_1} \left(0 + r_2 + \frac{3(r_3)}{L_1} \right)$$

$$M_{BA} = \frac{2EI}{L_1} \left(2r_2 + 0 + \frac{3(r_3)}{L_1} \right)$$

$$M_{BC} = \frac{2EI}{L_2} (2r_2 + r_1 + 0)$$

$$M_{CB} = \frac{2EI}{L_2} (2r_1 + r_2 + 0)$$

$$M_{CD} = \frac{2EI}{L_3} \left(\cancel{2r_1} + 0 + \frac{3(+r_3)}{L_3} \right)$$

$$M_{DC} = \frac{2EI}{L_3} \left(0 + r_1 + \frac{3(+r_3)}{L_3} \right)$$

⇒ WHY ⊖



+ r_3 CAUSES ⊖ MOMENTS

⇒ WHY ⊕



+ r_3 CAUSES

⊕ MOMENTS

EXAMPLE 2 CONT.

NOW PLUG M_{ij} INTO EQUILIBRIUM EQS.

$$r_1 = 1 \quad r_2 = 0 \quad r_3 = 0$$

$$K_{11} = M_{cB} + M_{cC} = \frac{4EI}{L_2} + \frac{4EI}{L_3} = K_{11}$$

$$K_{21} = M_{BA} + M_{BC} = \frac{4EI}{L_1} + \frac{4EI}{L_2} = K_{21}$$

$$K_{31} = \frac{M_{cD} + M_{cC}}{L_3} - \frac{M_{AB} + M_{BA}}{L_1} = \frac{4EI}{L_3} + \frac{2EI}{L_3} = K_{31}$$

$$r_1 = 0 \quad r_2 = 1 \quad r_3 = 0$$

$$K_{12} = M_{cB} + M_{cC} = \frac{2EI}{L_2} = K_{12}$$

$$K_{22} = M_{BA} + M_{BC} = \frac{4EI}{L_1} + \frac{4EI}{L_2} = K_{22}$$

$$K_{32} = \frac{M_{cD} + M_{cC}}{L_3} - \frac{M_{AB} + M_{BA}}{L_1} = 0 - \left(\frac{2EI}{L_1} + \frac{4EI}{L_1} \right) = K_{32}$$

$$r_1 = r_2 = 0 \quad r_3 = 1$$

$$K_{13} = M_{cB} + M_{cC} = \frac{6EI}{L_3} = K_{13}$$

$$K_{23} = M_{BA} + M_{BC} = -\frac{6EI}{L_1} = K_{23}$$

$$K_{33} = \frac{M_{cD} + M_{cC}}{L_3} - \frac{M_{AB} + M_{BA}}{L_1} = \frac{12EI}{L_3^2} + \frac{12EI}{L_1^2}$$

EXAMPLE 2 CONT.

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PUT RESULTS IN MATRIX

$$K = \begin{bmatrix} \frac{4EI}{L_2} + \frac{4EI}{L_3} & \frac{2EI}{L_2} & \frac{6EI}{L_3^2} \\ \frac{2EI}{L_2} & \frac{4EI}{L_1} + \frac{4EI}{L_2} & -\frac{6EI}{L_1^2} \\ \frac{6EI}{L_3^2} & -\frac{6EI}{L_1^2} & \frac{12EI}{L_1^3} + \frac{12EI}{L_3^3} \end{bmatrix}$$

CHECK FOR SYMMETRY

$$K_{12} = K_{21} \quad \checkmark$$

$$K_{23} = K_{32} \quad \checkmark$$

$$K_{13} = K_{31} \quad \checkmark$$

CHECK DIAGONALS POSITIVE

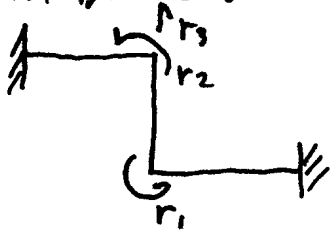
$$K_{11}, K_{22}, K_{33} \text{ ALL } \oplus \quad \checkmark$$

LOADS

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- POINT LOADS AND POINT MOMENTS
- DISTRIBUTED LOADS



$$K \begin{bmatrix} r_1 \\ r_2 \\ r_3 \end{bmatrix} = \begin{bmatrix} R_1 \\ R_2 \\ R_3 \end{bmatrix}$$

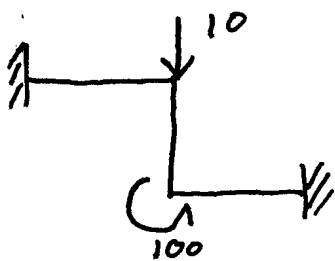
$K \quad 3 \times 3$

r = DISPLACEMENTS AT D.O.F.

R = LOADS AT D.O.F.

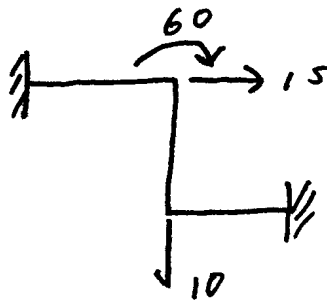
SOLVING $K \cdot r = R$

LOADS ONLY SHOW UP IN EQUATION AT D.O.F.



$$R = \begin{bmatrix} 100 \\ 0 \\ -10 \end{bmatrix}$$

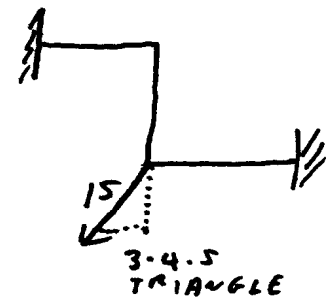
$\downarrow 10$ OPPOSITE DIRECTION FROM $\uparrow r_2$



$$R = \begin{bmatrix} 0 \\ -60 \\ -10 \end{bmatrix}$$

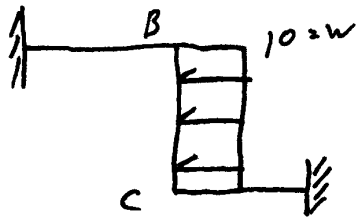
$\rightarrow 15$ NOT AT A D.O.F. (IGNORING AXIAL)
 $\uparrow r_3 \quad \downarrow r_2$

$\downarrow 10$ AT B O R C IS SAME

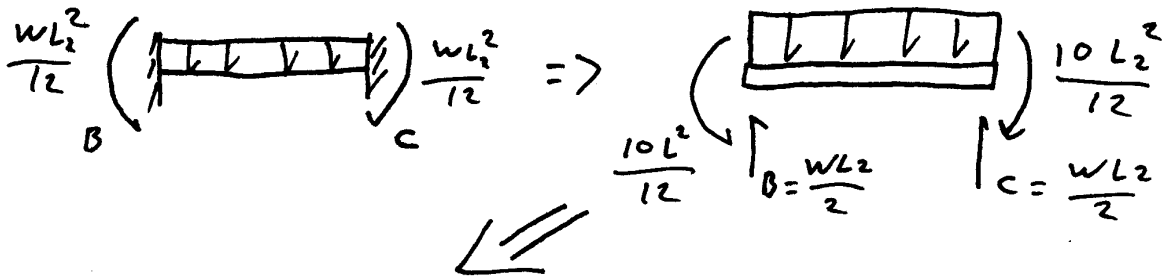


$$R = \begin{bmatrix} 0 \\ 0 \\ -15 \left(\frac{4}{5} \right) \end{bmatrix}$$

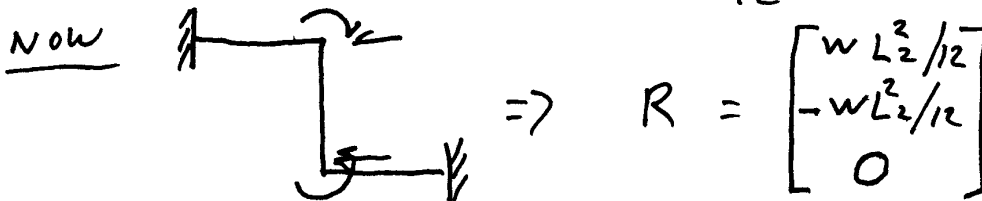
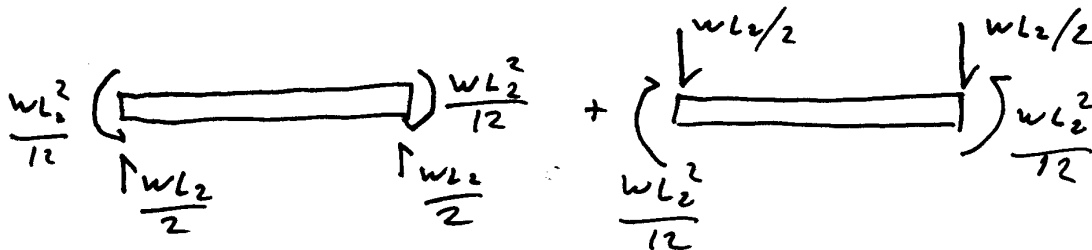
LOADS BETWEEN ENDS OF MEMBERS
MUST BE RESOLVED TO
EQUIVALENT NODAL LOADS
USING F, E, M.



SOLVE FOR SHEAR REACTION



GET RID OF DIST. LOAD
REPLACE WITH NODAL
LOADS THAT REQUIRE
SAME REACTIONS

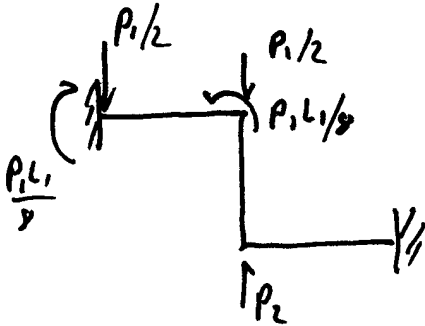
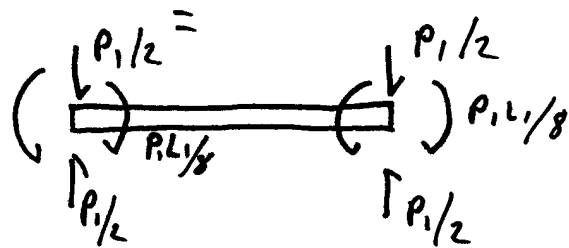
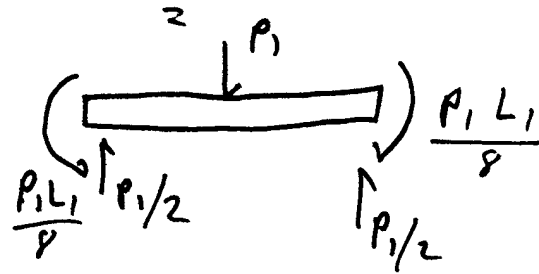
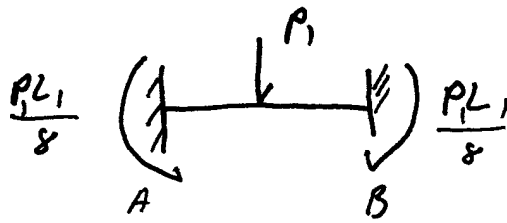
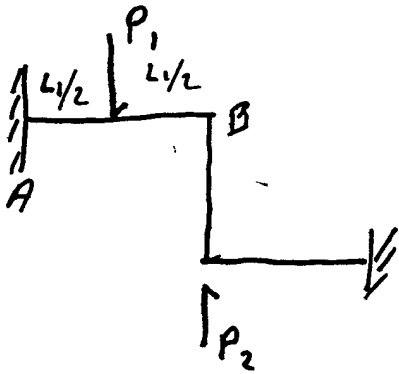


EQUIVALENT NODAL LOADS

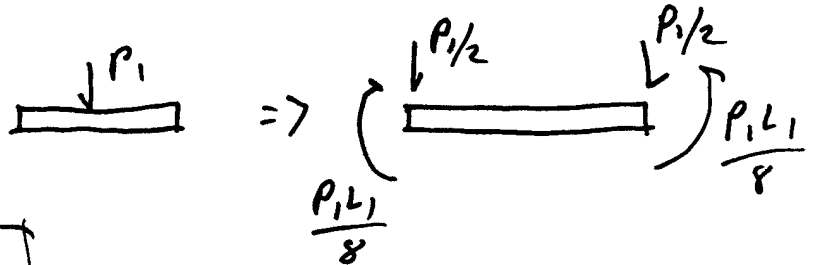
LOADS CONT.

CES 4141 (20)

EQUIV. NODAL LOADS



∴ EQUIVALENT NODAL LOADS



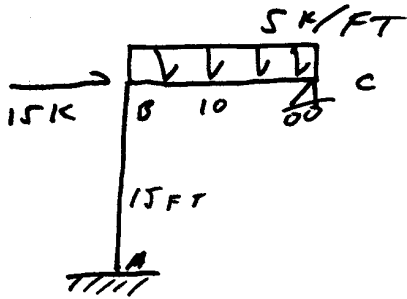
$$R = \begin{bmatrix} 0 \\ P_1 L_1 / 8 \\ -P_1 / 2 + P_2 \end{bmatrix}$$

SUPERIMPOSE MULTIPLE LOADS AT SAME D.O.F.

$$K \cdot r = R$$

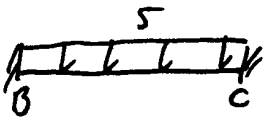
EXAMPLE #1 w/LOADS
 BACK TO EXAMPLE 1
 ADD LOADS

CES 4141 (21)



$$K = \begin{bmatrix} \frac{4EI}{L_{AB}} + \frac{4EI}{L_{BC}} & \frac{2EI}{L_{BC}} & \frac{6EI}{L_{AB}^2} \\ \frac{2EI}{L_{BC}} & \frac{4EI}{L_{BC}} & 0 \\ \frac{6EI}{L_{AB}^2} & 0 & \frac{12EI}{L_{AB}^3} \end{bmatrix}$$

GET R

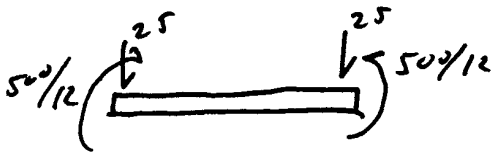


REACTIONS

$$\left(\begin{array}{c} \text{---} \end{array} \right) \frac{wL^2}{12} = \frac{500}{12}$$

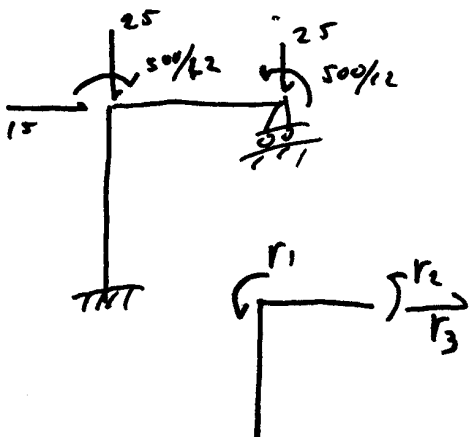
↑₂₅ ↑₂₅

EQUIVALENT
 NODAL LOADS



APPLY EQUAL &
 OPPOSITE OF REACTION
 AL LOADS

NEW PICTURE



$$R = \begin{bmatrix} -500/12 \\ 500/12 \\ 15 \end{bmatrix}$$

↓²⁵ LOADS
 NOT AT A
 D.O.F.

EXAMPLE 1 CONT.

CES 4141

(22)

NOW LET'S ADD #'S IN K & SOLVE

$E = 29000 \text{ KSI}$

$I = 400 \text{ IN}^4$

$L_{AB} = 15 \text{ FT}$

$L_{BC} = 10 \text{ FT}$

ALL CONVERTED
TO IN, K



$$\begin{bmatrix} 6.44 & 1.93 & 0.0215 \\ 1.93 & 3.866 & 0 \\ 0.0215 & 0 & .0002 \end{bmatrix} \begin{bmatrix} r_1 \\ r_2 \\ r_3 \end{bmatrix} = \begin{bmatrix} -500 \\ 500 \\ 15 \end{bmatrix}$$

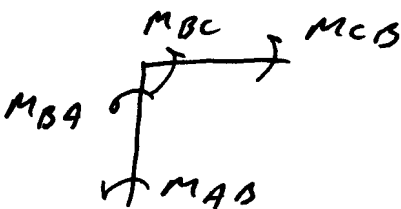
$\times 10^5$

USE H.P. OR GAUSS ELIMINATION

$r_1 = -0.0059 \text{ RAD}$
$r_2 = 0.0043 \text{ RAD}$
$r_3 = 1.1617 \text{ IN IN}$

NOW WE HAVE \uparrow ALL DISPLACEMENTS

WE CAN GO GET INTERNAL MOMENTS
 & REACTIONS



$$M_{AB} = \frac{2EI}{L_{AB}} \left(2\theta_A + \theta_B + \frac{3\Delta}{L} \right) + 0$$

$$M_{BA} = \frac{2EI}{L_{AB}} \left(2(-0.0059) + 0 + \frac{3(1.1617)}{L_{AB}} \right) + 0$$

$$M_{BC} = \frac{2EI}{L_{BC}} \left(2(-0.0059) + 0.0043 \right) + 500 \text{ K}\cdot\text{IN}$$

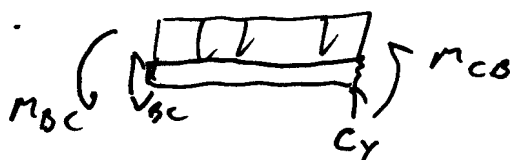
$$M_{CB} = \frac{2EI}{L_{BC}} \left(2(0.0043) - 0.0059 \right) - 500 \text{ K}\cdot\text{IN}$$

GET #'S,

$M_{AB} = M_A$ REACTION

FIND INTERNAL SHEARS

E.G.



ETC...